

Probability

Modeling uncertainty

Michael Psenka

Random experiment (random variable)

Elements of probability theory

Sample space

Definition. *For a “random experiment”, the sample space Ω is the set of possible outcomes of the random experiment.*

Events

Definition. *An event of a random variable with sample space Ω is a subset $E \subset \Omega$.*

Distribution

Definition. *A distribution $\pi : \mathcal{P}(\Omega) \rightarrow \mathbb{R}$ over a sample space Ω is a function of subsets of Ω that satisfies the following properties:*

1. *“Normalization”*: $\pi(\emptyset) = 0, \pi(\Omega) = 1$.
2. *“Monotonicity”*: $A \subset B \Rightarrow \pi(A) \leq \pi(B)$.
3. *“Additivity”*: $A \cap B = \emptyset \Rightarrow \pi(A \cup B) = \pi(A) + \pi(B)$.

Measure-theoretic definition

1 PROBABILITY SPACES AND RANDOM VARIABLES

Let $(\Omega, \mathcal{H}, \mathbb{P})$ be a probability space. The set Ω is called the *sample space*; its elements are called *outcomes*. The σ -algebra \mathcal{H} may be called the *grand history*; its elements are called *events*. We repeat the properties of the probability measure \mathbb{P} ; all sets here are events:

1.1 *Norming:* $\mathbb{P}(\emptyset) = 0, \quad \mathbb{P}(\Omega) = 1.$

Monotonicity: $H \subset K \Rightarrow \mathbb{P}(H) \leq \mathbb{P}(K).$

Finite additivity: $H \cap K = \emptyset \Rightarrow \mathbb{P}(H \cup K) = \mathbb{P}(H) + \mathbb{P}(K).$

Countable additivity: (H_n) disjoint $\Rightarrow \mathbb{P}(\bigcup_n H_n) = \sum_n \mathbb{P}(H_n).$

Sequential continuity: $H_n \nearrow H \Rightarrow \mathbb{P}(H_n) \nearrow \mathbb{P}(H),$
 $H_n \searrow H \Rightarrow \mathbb{P}(H_n) \searrow \mathbb{P}(H).$

Boole's inequality: $\mathbb{P}(\bigcup_n H_n) \leq \sum_n \mathbb{P}(H_n).$

Erhan Çinlar, *Probability and Stochastics* (you will not be tested on this)

Distribution (notes)

Definition. A distribution $\mathbb{P}: \mathcal{P}(\Omega) \rightarrow \mathbb{R}$ over a sample space Ω is a function of subsets of Ω , first defined over the singletons $\{a\}, a \in \Omega$ such that:

1. $\mathbb{P}(A) = \sum_{a \in A} \mathbb{P}(a),$
2. $0 \leq \mathbb{P}(a) \leq 1$ for all $a \in \Omega,$
3. $\mathbb{P}(\Omega) = \sum_{a \in \Omega} \mathbb{P}(a) = 1.$

Equivalence of definitions

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Random variables

Definition. *A random variable is a double $X = (\Omega, \pi)$, where Ω is the sample space of X , and π is the distribution of X .*

Examples of random variables

Example: balls and bins

Example: “birthday paradox”

Example: Monty Hall problem